

### Contents

- Strange Rotations from MoCap
- Correction Methods

# Overview

This document covers how to correct animation (specifically rotations) in MotionBuilder based on the fact the input will be a control rig from motion capture data ...

# Rotations

### Introduction

- Rotations can be a nightmare from Motion Capture data because they are not easily visible until you have applied the control rig to a skinned character
- Once they are applied, we end up with twists (mainly at elbow joints, but also wrists and knees too); an example is shown below



### Rotations

### Introduction

- We can correct this using several methods, but we shall cover 3 of the easiest methods here (at least easiest to explain)
- First, let's look at the problem; the problem usually consists of +/- flip, so one key frame the rotation for a specific axis is positive and the next it is negative
- In general, this doesn't have to be the same value on either side (although sometimes it can be indicating a gimbal problem), but just a "crazy" rotation

# Rotations

### Introduction

- What is a "crazy" rotation?
- Well, let us look at the normal limits of the arm; in general our elbow for example will rotate between +65 and -65 degrees (approximately 130 degrees rotation end-toend)
- A crazy rotation would be between two frames approaching or greater than this (so certainly a difference in rotation of 200 degrees would be considered "crazy")

### Rotations

- Introduction
  - Another "crazy" rotation would be outside the joint limits; as previously discussed the limits are about +65 to -65, so if the rotation is further than this, then it is going outside the limit
  - However, this relies on the fact that the 0 degree rotation point is where the palm is flat to the floor (in the T-pose) which often it's not
  - Therefore, you have to use your own judgment here ...

### Rotations



### **Rotations**

- F-Curves
  - We can see in the previous slide that the curve is nice and steady at almost 0 degrees and then in almost less than 1 keyframe it shifts to 100 degrees (very fast) and then 5 keyframes later it shifts another 100 degrees
  - Well, if 0 is the centre of the rotation then we should be expecting a maximum of +/- 180 limits (which does limit us) but this is an extreme and therefore unexpected
  - This is also the rotation on the elbow joint, thus impossible for a normal human ...

# Correction Methods

### Introduction

- So, how do we correct this? It is import to preserve as much data as possible without leaving this impossible rotation in our animation sequence
- Here we introduce 3 methods
  - Degree of Freedom Limits
  - Data Filtering
  - Key Frame Correction of FK

# **Correction Methods**

- Setting Up the Character
  - First, you obviously need to load in your character into MotionBuilder
  - Once that is done, click on the "viewer" window and under the "Display" drop-down menu (top/left) select "X-Ray"
  - If you end up with a lot of circles surrounding your joints (sometimes yes, sometimes not) then you can turn them off by using "Display"
     → "Models Visibility" and uncheck "Skeletons"

# **Correction Methods**

### Setting Up the Character

- In general, we can scroll through the timeline until we get to the problem that we need to correct
- At this point, it is best to select the joint that is causing us this problem in order that we can edit its properties
- Before we do that, we need to turn off the IK control elements; we do this under the "Character Controls" window:
  - "Show" dropdown menu → uncheck "IK"





























# Correction Methods

### Filtering

- Filtering can be useful to edit noise and there are other functions there (which should be used with care)
- We can apply these filters on the entire set of frames, and all curves, or just a selection (which is more appropriate)

# **Correction Methods**

### Filtering

- The filters worth looking at are:
  - Peak Removal ~ which can removal spikes and peaks in your curves (often caused by errors in the data happening over 1 frame)
  - Butterworth ~ which sets the frequency in order to perform a noise removal function (similar to the Butterworth filter used by Vicon)
  - Gimbal Killer ~ if you are suffering from Gimbal problems, this can remove them (sometimes)

# **Correction Methods**

### Filtering

- The filters worth looking at are:
  - Peak Removal ~ which can removal spikes and peaks in your curves (often caused by errors in the data happening over 1 frame)
  - Butterworth ~ which sets the frequency in order to perform a noise removal function (similar to the Butterworth filter used by Vicon)
  - Gimbal Killer ~ if you are suffering from Gimbal problems, this can remove them (sometimes)
- All filters are subject to the conditions that exist, but they are easy to try and rest if you wish to see what happens...

# **Correction Methods**

- Degree of Freedom Limits
  - Lastly, another method which can help us correct some of the problems is to set the "degree of freedom" limits
  - Here we set the joint limits of each joint and thus limit the effect that a rotation has (note this doesn't recompute the Kinematics, it simply limits an input rotation from the control rig)

# **Correction Methods**

- Degree of Freedom Limits
  - In order to switch on DoF limits, we need to open the Properties (menu → "Window" → "Add Properties Editor") but it might already be up (near "Filters")
  - Each joint you select has different properties, so make sure you have selected the joint you wish to set the DoF on
  - Expand the joint, so you see "Visibility", "Transformation", etc and expand the tab "Degrees of Freedom" and you should see "Translation", "Rotation", and "Scaling"

### **Correction Methods**

- Degree of Freedom Limits
  - Open the tab "Rotation"
  - Firstly, if we want to enable DoF, we need to check the box called "Enable Rotation DoF"
  - Next, if we want to enable Limits, we need to check the box called "Enable MB5.5 Limits" this is simpler to understand than using "Pre-Rotation" etc
  - Now we have tabs for "Min R" and "Max R", we can open both

# Correction Methods Degree of Freedom Limits Here, we can limit each axis (X, Y, and Z) and switch them on/off using the check boxes The values (here shown as 0.00) can be set for the minimum and maximum values When we adjust them, we shall see that if our model is outside those links, it will shift the joint accordingly

